

Affine Focal Sets of Codimension 2 Submanifolds contained in Hypersurfaces

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Outline

Affine Differential Geometry

Curves contained in Surfaces in the Affine 3-Space

Envelope of Tangent Spaces of a Submanifold $N^n \subset M^{n+1} \subset \mathbb{R}^{n+2}$

Affine Geometry of a Submanifold $N^n \subset M^{n+1} \subset \mathbb{R}^{n+2}$

Parallel Darboux Vector Fields

Affine Focal Set of an Immersion $N \subset M$

Some Classes of Immersions

Umbilic Immersions

Next Section

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Affine Differential Geometry

The Affine Differential Geometry of hypersurfaces is classical:
Tzitéica (1908), Blaschke, Radon, Pick, Berwald, Thomsen
(1916-1923), Cartan (1924), Kubota, Süss, Su Buchin, Nakajima
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For higher codimensions, there are much less theory: Burstin-Mayer (1927), Weise (1939), Klingenberg (1951), Nomizu-Vrancken (1993).

References:

- ▶ Buchin, S.: Affine Differential Geometry, 1983.
- ▶ Nomizu, K., Sasaki, T.: Affine Differential Geometry, 1994.

Codimension 2 submanifolds contained in a hypersurface

We shall discuss here the case of codimension 2 submanifolds N contained in hypersurface M .

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In fact, we need only the hypersurface M around the submanifold N , or equivalently, the submanifold N together with a tangent space (to M) at each point.

We can also think of submanifolds N together with a distinguished transversal vector field ξ (tangent to M).

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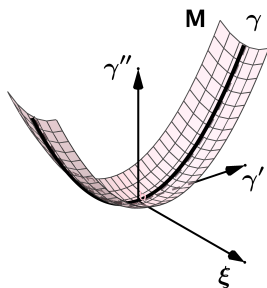
Darboux direction

Let $\gamma \subset M$ be a smooth curve contained in a surface $M \subset \mathbb{R}^3$.

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Assume that the osculating plane of γ does not coincide with the tangent plane of M . There exists a unique direction ξ tangent to M and transversal to γ such that $D_X \xi$ is tangent to M , for any X tangent to γ . This direction is called the **(osculating) Darboux direction** of $\gamma \subset M$.



Affine metric and affine normal plane

There exists a unique vector field $\xi(t)$ in the Darboux direction which is **parallel**, i.e., $\xi'(t)$ is tangent to $\gamma(t)$, $t \in I$.

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$$[\gamma'(t), \gamma''(t), \xi(t)] = 1.$$

Then $\gamma'''(t)$ is tangent to M .

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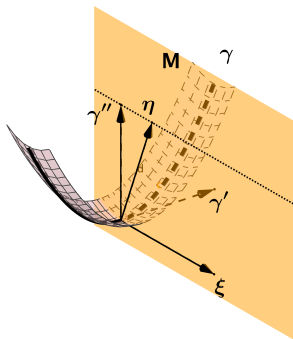
The Darboux-Frenet equations for the frame $\{\gamma'(t), \gamma''(t), \xi(t)\}$ are

$$\begin{cases} (\gamma')' = \gamma'', \\ (\gamma'')' = -\rho\gamma' + \tau\xi, \\ \xi' = -\sigma\gamma'. \end{cases}$$

A parallel basis for the affine normal plane

Choose $\lambda(t)$ such that $\lambda'(t) = -\tau(t)$. Observe that λ may not be globally defined for closed curves. Define

$$\eta(t) = \gamma''(t) + \lambda(t)\xi(t).$$



New Darboux-Frenet equations

We have

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where $\mu(t) = \rho(t) + \lambda(t)\sigma(t)$.

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$$\begin{cases} \gamma'' = \eta - \lambda\xi, \\ \eta' = -\mu\gamma', \\ \xi' = -\sigma\gamma'. \end{cases}$$

Envelope of Tangent Planes

The **Envelope of Tangent Planes** of M along γ is parameterized by

$$\phi(t, u) = \gamma(t) + u\xi(t), \quad t \in I, \quad u \in \mathbb{R},$$

where $\xi(t)$ is the Darboux direction. It is also called **Osculating Developable Surface**.

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The Envelope of Tangent Planes reduces to a point if and only if $\sigma = -1$, constant, and $\xi = \gamma$ (**centro-affine geometry**). This case is of particular interest in Computer Vision, since the curves are **silhouette curves** or **visual contours** of an object. They are also called **non-brightening curves** (K. Saji).

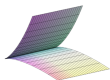
Singularities of the Envelope of Tangent Planes

1) If $u \neq \sigma^{-1}(t)$, ϕ is smooth.

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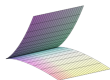
2) If $\sigma(t) \neq 0$, $u = \sigma^{-1}(t)$ and $\sigma'(t) \neq 0$, then ϕ is locally diffeomorphic to a cuspidal edge.



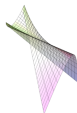
Singularities of the Envelope of Tangent Planes

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2) If $\sigma(t) \neq 0$, $u = \sigma^{-1}(t)$ and $\sigma'(t) \neq 0$, then ϕ is locally diffeomorphic to a cuspidal edge.



3) If $\sigma(t) \neq 0$, $u = \sigma^{-1}(t)$, $\sigma'(t) = 0$ and $\sigma''(t) \neq 0$, then ϕ is locally diffeomorphic to a swallowtail.



Affine Focal Sets

The equation of the affine normal plane at $\gamma(t)$ is $F(x, t) = 0$, where

$$F(x, t) = [x - \gamma(t), \eta(t), \xi(t)]$$

The envelope of the affine normal planes is the set

$$\mathcal{B} = \{x \in \mathbb{R}^3 \mid F = F_t = 0, \text{ for some } t \in I\}.$$

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$$\mathcal{B} = \{x \in \mathbb{R}^3 \mid F = F_t = 0, \text{ for some } t \in I\}.$$

Observe that \mathcal{B} is also the bifurcation set of the affine distance function

$$\Delta(x, t) = [x - \gamma(t), \gamma'(t), \xi(t)].$$

The set \mathcal{B} is also called **affine focal set** or **evolute** of the immersion $\gamma \subset M$.

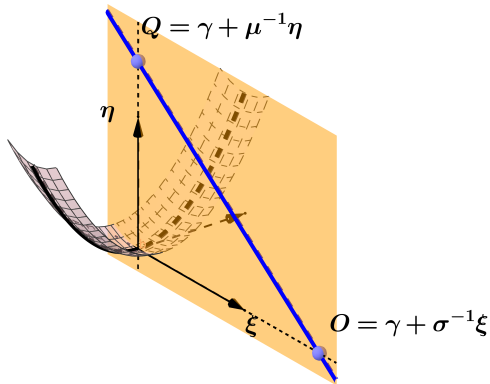
The affine focal set is a developable surface

We have that

$$\mathcal{B} = \{l(t) \mid t \in I\},$$

where $l(t)$ denote the line connecting

$$O(t) = \gamma(t) + \sigma^{-1}(t)\xi(t), \quad Q(t) = \gamma(t) + \mu^{-1}(t)\eta(t).$$



Singularities of the Affine Focal Set

The equation of the affine normal plane is

$$F(x, t) = [x - \gamma(t), \eta(t), \xi(t)].$$

Then $F = F_t = 0$ if and only if $x = \gamma(t) + u\eta(t) + v\xi(t)$ and

$$u\mu + v\sigma = 1.$$

If $F = F_t = 0$, then

$$F_{tt} = u\mu' + v\sigma'.$$

If $F = F_t = F_{tt} = 0$ then

$$F_{ttt} = u\mu'' + v\sigma''.$$

Finally if $F = F_t = F_{tt} = F_{ttt} = 0$, then

$$F_{tttt} = u\mu''' + v\sigma'''.$$

Singularities of the Affine Focal Set

Theorem

Let \mathcal{B} be the affine focal set of $\gamma \subset M$. Each point of \mathcal{B} at $\gamma(t)$ belongs to the line

$$u\mu + v\sigma = 1.$$

Then

1. \mathcal{B} is smooth if $u\mu' + v\sigma' \neq 0$.
2. \mathcal{B} is locally diffeomorphic to a cuspidal edge if $u\mu' + v\sigma' = 0$ and $u\mu'' + v\sigma'' \neq 0$.
3. \mathcal{B} is locally diffeomorphic to a swallowtail if $u\mu'' + v\sigma'' = 0$ and $u\mu''' + v\sigma''' \neq 0$.

Immersions whose affine focal set is a single line

The affine focal set \mathcal{B} reduces to a single line if and only if σ and μ are constants.

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The affine focal set \mathcal{B} reduces to a single line if and only if σ and μ are constants. Assuming $\sigma = -1$, we obtain $\xi = \gamma$ and so

$$\gamma'''(t) = -\rho(t)\gamma'(t) + \tau(t)\gamma(t).$$

The condition $\mu' = 0$ can be written as $\tau = -\rho'$. Thus

$$\gamma'''(t) = -(\rho(t)\gamma(t))',$$

or equivalently,

$$\gamma''(t) = -\rho(t)\gamma(t) + Q,$$

for some constant vector Q .

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for some constant vector Q .

Assume $Q = (0, 0, 1)$ and write $\gamma = (\psi, z)$. Then

$$\psi''(t) = -\rho(t)\psi(t); \quad z''(t) = -\rho(t)z(t) + 1.$$

Immersion whose affine focal set \mathcal{B} is a single line

Theorem: (C., M.J.Saia, L.Sánchez) For a planar curve Ψ , denote $\psi = \Psi'$ and $z(t) = [\Psi(t) - O, \psi(t)]$ (the **affine distance** or **support function** of Ψ with respect to an origin O). Then the affine focal set of the spacial curve

$$\gamma(t) = (\psi(t), z(t))$$

is a single line. Conversely, any curve $\gamma \subset M$ whose affine focal set is a single line is obtained by this construction.

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Since $\Psi''' = -\rho\Psi'$, ρ is the affine curvature of the planar curve Ψ . Moreover, $\rho' + \tau = 0$ and so $\rho' = 0$ if and only if $\gamma(t)$ is flat.

Corollary: Closed curves contained in surfaces whose affine focal set is a single line have at least six flat points.

A projectively invariant six vertex theorem

In the centro-affine case ($\sigma = -1$, $\xi = \gamma$), write

$$\gamma'''(t) = -\rho(t)\gamma'(t) + \tau(t)\gamma(t),$$

$$h(t) = \rho'(t) + 2\tau(t).$$

The cubic form $h(t)dt^3$ is projectively invariant and $h(t)^{1/3}dt$ is called the **projective arc-length**.

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If we represent γ by a planar curve, $\tau = 0$ and ρ is the affine curvature of γ . We conclude that any closed curve admit at least six points where $h(t) = 0$. Geometrically, this means that γ has higher order contact with a **quadratic cone** at least six times.

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Darboux direction

For $N^n \subset M^{n+1} \subset \mathbb{R}^{n+2}$, take $\{X_1, \dots, X_n\}$ a local frame of N , ξ tangent to M and transversal to N and η transversal to M . Write

$$D_X Y = \nabla_X Y + h^1(X, Y)\xi + h^2(X, Y)\eta.$$

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We say that the immersion is **non-degenerate** if the $n \times n$ matrix $(h^2(X_i, X_j))$ is non-degenerate. This condition is independent of the local frame of N , ξ and η .

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Under the non-degeneracy condition, there exists a unique direction ξ tangent to M such that $D_X \xi$ is tangent to M , for any $X \in TN$.

We shall call this direction the *Darboux direction* of $N \subset M$.

Envelope of Tangent Spaces

Let $\{X_1, \dots, X_n\}$ be a frame for TN . The tangent space of M at $p \in N$ is given by $F = 0$, where

$$F(x) = [x - p, X_1, \dots, X_n, \xi].$$

The **Envelope of Tangent Spaces** of $N \subset M$ is given by

$$ET_N(p, u) = p + u\xi(p), \quad p \in N, \quad u \in \mathbb{R}.$$

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$$ET_N(p, u) = p + u\xi(p), \quad p \in N, \quad u \in \mathbb{R}.$$

Write

$$D_X \xi = -S_\xi X + \tau_1^1(X)\xi$$

Then $ET_N(p, u)$ is smooth if $u \neq \sigma^{-1}$, for some non-zero eigenvalue σ of the shape operator S_ξ .

Envelope of Tangent Spaces- Simple Singularities

We show through examples that any simple singularity can appear in ET_N . We recall that any simple singularity is \mathcal{R} -equivalent to A_k , $k \geq 2$, D_k , $k \geq 4$, E_6 , E_7 or E_8 . (*)

(*) Equiaffine Darboux frames for codimension 2 submanifolds contained in hypersurfaces, M.Craizer, M.J.Saia, L.Sánchez, J.Math.Soc.Japan, 2016.

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Consider $M \subset \mathbb{R}^{n+2}$ given by the graph of $f(t, y)$, $t = (t_1, \dots, t_n)$. We shall assume that $f = f_{t_i} = f_y = 0$ at the origin, for any $1 \leq i \leq n$. Let N be the submanifold $y = g(t)$ and assume that $g_{t_i} = 0$ at $t = 0$, i.e., the tangent space of N is generated by $\{e_i\}$, $1 \leq i \leq n$.

(1) Let

$$f(t, y) = \frac{t^2}{2} + \frac{1}{6}t^3 + \frac{\sigma}{2}t^2y, \quad g(t) = 0,$$

Then, close to $(0, \sigma^{-1}, 0)$,

$$F(t, x_1, x_2 + \sigma^{-1}, x_3) = -\frac{1}{3}t^3 + \frac{\sigma}{2}t^2x_2 + \left(\frac{1}{2}t^2 + t\right)x_1 - x_3,$$

which is a versal unfolding of an A_2 point.

(2) Let

$$f(t, y) = \frac{t^2}{2} + \frac{1}{24}t^4 + \frac{\sigma}{2}t^2y, \quad g(t) = 0,$$

Close to $(0, \sigma^{-1}, 0)$,

$$F(t, x_1, x_2 + \sigma^{-1}, x_3) = -\frac{1}{8}t^4 + \frac{\sigma}{2}t^2x_2 + \left(\frac{1}{6}t^3 + t\right)x_1 - x_3,$$

which is a versal unfolding of an A_3 point.

(3) For general $k \geq 3$, let $\sigma = 1$, $t = (t_1, \dots, t_{k-2})$, i.e., $n = k - 2$,

$$f(t, y) = \frac{1}{2}|t|^2 + \frac{1}{2}t_1^2 y + \sum_{j=2}^{k-2} t_1^{j+1} t_j,$$

$$g(t) = -t_1^{k-1} - \sum_{j=2}^{k-2} (j+1)t_1^{j-1} t_j$$

Then, close to $(0, \dots, 1, 0)$,

$$F = t_1^{k+1} - \frac{1}{2} \sum_{j=2}^{k-2} t_j^2 + x_1(t_1 - t_1^k) + \sum_{j=2}^{k-2} x_j(t_j + t_1^{j+1}) + \frac{1}{2} t_1^2 x_{k-1} - x_k.$$

which is a versal unfolding of an A_k point.

(4) For a general $k \geq 4$, take

$$f = \frac{1}{2}|t|^2 + \frac{y}{2}(t_1^2 + t_2^2) + t_1^{k-1} + t_1 t_2^2 + \sum_{j=3}^{k-2} t_1^j t_j + \sum_{j=3}^{k-2} t_1^{j-2} t_2^2 t_j$$

and $g = -\sum_{j=3}^{k-2} j t_j t_1^{j-2}$. Long but straightforward calculations show that, close to $(0, \dots, 1, 0)$,

$$\begin{aligned} F = & (2-k)t_1^{k-1} - 2t_1 t_2^2 - \frac{1}{2} \sum_{j=3}^{k-2} t_j^2 - x_k + \frac{1}{2}(t_1^2 + t_2^2)x_{k-1} \\ & + \sum_{j=3}^{k-2} x_j(t_1^j + t_1^{j-2} t_2^2 + t_j) + x_2 \left(t_2 + 2t_1 t_2 + \sum_{j=3}^{k-2} (2-j)t_1^{j-2} t_2 t_j \right) \\ & + x_1 \left(t_1 + (k-1)t_1^{k-2} + t_2^2 + \sum_{j=3}^{k-2} (j-2)t_1^{j-3} t_2^2 t_j \right), \end{aligned}$$

which is a versal unfolding of a D_k point.

(5) Consider

$$f = \frac{1}{2}|t|^2 + \frac{1}{2}(t_1^2 + t_2^2)y + t_1^3 + t_2^4 + t_1 t_2 t_3 + 2t_1 t_2 t_3 y + t_1 t_2^2 t_4 + 3t_1 t_2^2 t_4 y$$

and $g = 0$. Then

$$\begin{aligned} F = & -2t_1^3 - 3t_2^4 - \frac{1}{2}(t_3^2 + t_4^2) - x_6 + x_4(t_1 t_2^2 + t_4) + x_3(t_1 t_2 + t_3) \\ & + x_1(t_1 + 3t_1^2 + t_2^2 t_4 + t_2 t_3) + x_2(t_2 + 4t_2^3 + t_1 t_3 + 2t_1 t_2 t_4) \\ & + x_5\left(\frac{1}{2}(t_1^2 + t_2^2) + 2t_1 t_2 t_3 + 3t_1 t_2^2 t_4\right) \end{aligned}$$

which is a versal unfolding of an E_6 point.

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Umbilic Immersions

Affine metric associated with a vector field

Let ξ be a fixed vector field in the osculating Darboux direction.
For a local frame $\{X_1, \dots, X_n\}$ of TN and $X, Y \in TN$ define

$$G(X, Y) = [X_1, \dots, X_n, D_X Y, \xi].$$

Then

$$g(X, Y) = \frac{G(X, Y)}{\det G(X, Y)^{\frac{1}{n+2}}}$$

is a non-degenerate metric in N , called **affine metric** (*).

(*) Luis F. Sánchez: *Surfaces in 4-space from the affine differential viewpoint*, Ph.D. thesis, 2014. Advisors: M.J.Saia and J.J.Nuño-Ballesteros.

Affine normal plane bundle

There exists a vector field η transversal to M such that

1. For any $X \in TN$, $D_X\eta$ is tangent to M .
2. For any g -orthonormal frame $\{X_1, \dots, X_n\}$ of TN .

$$[X_1, \dots, X_n, \eta, \xi] = 1.$$

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The transversal vector field η satisfying the above conditions is not unique, any vector field of the form

$$\bar{\eta} = \eta + \lambda\xi$$

satisfies the same conditions. But, up to these transformations, it is unique. The transversal bundle $\mathcal{S}\{\xi, \eta\}$ is called the **affine normal plane bundle**.

Semi-umbilic immersions

For ν in the affine normal plane bundle and $X \in TN$ write

$$D_X \nu = -S_\nu X + \nabla_X^\perp \nu,$$

where $S_\nu X$ is tangent to N and $\nabla_X^\perp \nu$ belongs to the affine normal plane. The linear map S_ν is called **shape operator** and $\nabla_X^\perp \nu$ is called **affine normal connection**. The immersion $N \subset M$ is **semi-umbilic (umbilic)** if $S_\nu = \lambda Id$, for some (any) vector field ν in the affine normal plane bundle.

Semi-umbilic immersions

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Proposition: (J.J.Nuño-Ballesteros, L.Sánchez) If $N \subset M$ is semi-umbilic at $p \in N$, the shape operators S_ν at p commute. The converse holds if $n = 2$.

Next Section

Affine Differential Geometry

Curves contained in Surfaces in the Affine 3-Space

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Trançon planes

Consider a point p in a surface M and a tangent vector $T \in T_p M$. A very classical result of A. Trançon (1841) says that the affine vectors at p of all sections of M containing T belongs to a plane $A(p, T)$. This plane is called the **Trançon** plane.

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This result can be generalized to hypersurfaces M by considering sections containing a hyperplane $H \subset T_pM$.

Theorem: (*) Consider an immersion $N \subset M$ and denote by H the tangent space of N at p . The affine normal plane $A(p, \xi)$ coincides with the Trançon plane $A(p, H)$ if and only if ξ is parallel.

(*) Equiaffine Darboux frames for codimension 2 submanifolds contained in hypersurfaces, M.Craizer, M.J.Saia, L.Sánchez, J.Math.Soc.Japan, 2016.

Cubic forms and the apolarity condition

The cubic forms are defined as

$$C^1(X, Y, Z) = (\nabla_X h^1)(Y, Z) + \tau_1^1(X)h^1(Y, Z) + \tau_2^1 h^2(Y, Z)$$

$$C^2(X, Y, Z) = (\nabla_X h^2)(Y, Z) + \tau_1^2(X)h^1(Y, Z) + \tau_2^2 h^2(Y, Z)$$

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The cubic form C^2 is **apolar** with respect to h^2 if

$$\text{tr}_{h^2} C^2(X, \cdot, \cdot) = 0$$

for any $X \in TN$.

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Proposition: The vector field ξ is parallel if and only if the cubic form C^2 is apolar with respect to h^2 .

The Laplacian operator

Let $\phi : U \rightarrow \mathbb{R}^{n+2}$ be a parameterization of N and denote by Δ the Laplacian operator with respect to the metric g .

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Let $\phi : U \rightarrow \mathbb{R}^{n+2}$ be a parameterization of N and denote by Δ the Laplacian operator with respect to the metric g .

Proposition: $\Delta\phi$ belongs to the affine normal plane if and only if the Darboux vector field is parallel.

Sketch of proof: Write

$$D_X\phi_*Y - \phi_*(\hat{\nabla}_X Y) = \phi_*(K(X, Y)) + h^1(X, Y)\xi + h^2(X, Y)\eta,$$

where $K(X, Y) = \nabla_X Y - \hat{\nabla}_X Y$. The apolarity condition can be stated as $tr_g(K) = 0$. So

$$\Delta\phi = (tr_g h^1)\xi + n\eta.$$

Affine normal plane bundle- Discussion

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From the point of view of Affine Focal Sets, the right choice is the affine normal plane bundle.

Next Section

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Umbilic Immersions

Affine distance to M along N

Let $\phi : U \rightarrow \mathbb{R}^{n+2}$ be a parameterization of N . Define $F : U \times \mathbb{R}^{n+2} \rightarrow \mathbb{R}$ by

$$F(t, x) = [X_1(t), \dots, X_n(t), \xi(t), x - \phi(t)],$$

where $X_i(t) = \phi_{t_i}(t)$.

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Proposition: The singular set of F coincides with the affine normal plane at $\phi(t)$.

Affine Focal Set of the immersion $N \subset M$

The **bifurcation set** of F is defined by

$$\mathcal{B} = \{x \in \mathbb{R}^{n+2} \mid \det(D_{tt}F) = 0\}.$$

where $D_{tt}F$ denotes the hessian matrix of $F(\cdot, x)$. The set \mathcal{B} is also called the **affine focal set** of the immersion $N \subset M$.

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Proposition: If the immersion is semi-umbilic at a point, the affine focal set consists of n lines at this point.

Example: Product of two curves

Let $\alpha(u)$ and $\beta(v)$ be planar curves parameterized by affine arc-length and consider $\phi : I \times J \rightarrow \mathbb{R}^4$ given by

$$\phi(u, v) = (\alpha(u), \beta(v)).$$

Choose

$$\xi = (\alpha''(u), \beta''(v))$$

as a parallel Darboux vector field and consider

$$\xi_1 = (\alpha''(u), 0); \quad \xi_2 = (0, \beta''(v))$$

as a parallel basis for the affine normal plane bundle. Then

$$\mathcal{B} = \{x = \phi + r\xi_1 + s\xi_2 \mid s = k(\alpha)^{-1} \text{ or } r = k(\beta)^{-1}\},$$

where k denotes affine curvature. At a point $\phi(u, v)$, \mathcal{B} consists of two concurrent lines. Globally,

$$\mathcal{B} = E(\alpha) \times \mathbb{R}^2 \cup \mathbb{R}^2 \times E(\beta).$$

Next Section

Affine Differential Geometry

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Hyperplanar Submanifolds

If N is contained in a hyperplane H , we may choose ξ in the Darboux direction with a constant component in fixed direction transversal to H . This ξ is a parallel Darboux vector field. With this choice of ξ , g coincides with the Blaschke metric of $N \subset H$.

Proposition: The affine Blaschke normal η of $N \subset H$ belongs to the affine normal plane.

Corollary 1: η is umbilic if and only if $N \subset H$ is an affine sphere.

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Corollary 2: $N \subset M$ is umbilic if and only if $N \subset H$ is an affine sphere and the envelope of tangent spaces of $N \subset M$ is a cone.

Affine Focal Set- Simple Singularities

It is shown in (*) that all simple singularities appear for the affine focal set of hypersurfaces. Thus they also appear for the affine focal set of $N \subset M \subset \mathbb{R}^{n+2}$.

(*) D.Davis- Thesis- University of Liverpool, 2008

Visual contour submanifolds

Suppose all tangent planes along N meet at a point O . Taking

$$\xi(p) = \phi(p) - O,$$

we obtain $D_X \xi = X$. So ξ is parallel and $S_1 = -Id$.

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Proposition: $N \subset M$ is a visual contour if and only if there exists a parallel Darboux vector field that is also umbilic.

This class of immersions is an object of study of the **centro-affine differential geometry** of codimension 2 submanifolds.

Submanifolds contained in hyperquadrics

If M is a hyperquadric and $N \subset M$ is arbitrary, take ξ h -orthogonal to TN satisfying $h(\xi, \xi) = 1$, where h is the Blaschke metric of M . Then ξ is a parallel Darboux vector field. With this ξ , g coincides with the restriction to N of the Blaschke metric of M .

Proposition: (J.J.Nuño-Ballesteros-M.J.Saia-L.Sánchez) The affine Blaschke normal $\eta = \phi - Q$ belongs to the affine normal plane, is parallel and umbilic.

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Proposition: $N \subset M$ is umbilic if and only if it is contained in a hyperplane.

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Differential equation of umbilic immersions

Assume $\xi = \phi$. The immersion $\phi \subset M$ is **umbilic** if there exists some constant vector $Q \neq O$ that belongs to the affine normal plane $A(t)$, for any $t \in U$. This is equivalent to say that for some (and hence any) g -orthonormal frame $\{X_1, \dots, X_n\}$ of $N = \phi(U)$, we have

$$[\phi, X_1, \dots, X_n, Q] = 1.$$

This is equivalent to

$$\frac{1}{n} \Delta \phi = -\lambda \phi + Q,$$

for some constant vector Q .

Affine distance to a hypersurface in the $(n + 1)$ -space

Consider a non-degenerate immersion $f : U \subset \mathbb{R}^n \rightarrow \mathbb{R}^{n+1}$ and fix $O \in \mathbb{R}^{n+1}$. Denote by $\nu : U \rightarrow \mathbb{R}_*^{n+1}$ the co-normal map of f . Define $\phi : U \rightarrow \mathbb{R}^{n+2}$ by

$$\phi(t) = (\nu(t), \nu(t) \cdot (f(t) - O)),$$

where $\nu(t) \cdot (f(t) - O)$ is the **affine distance** or **support function** of f with respect to the origin O .

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Theorem: The immersion ϕ is umbilic. Conversely, any umbilic immersion is given by the above equation, for some immersion f and origin O .

Contact with hyperquadrics

Proposition: Assume that f is compact. Then ϕ is contained in a hyperplane if and only if f is a n -dimensional ellipsoid.

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Proof. For a n -dimensional ellipsoid and O its center, the affine distance is constant. Conversely, if the affine distance is constant, then the affine evolute of f is a point and f is totally umbilic. Thus f is an affine sphere, and a compact affine sphere is an ellipsoid.

Sketch of proof

Let $\{X_1, \dots, X_n\}$ be a h -orthonormal frame.

$$\phi = (\nu, \nu \cdot (f - O)), \quad \phi_* X = (\nu_* X, \nu_* X \cdot (f - O)),$$

$$D_X \phi_* Y = (D_X \nu_* Y, D_X \nu_* Y \cdot (f - O)) - h(X, Y)Q.$$

Writing

$$D_X \nu_* Y = \sum_{i=1}^n a_i \nu_* X_i + b\nu,$$

$$(D_X \nu_* Y, D_X \nu_* Y \cdot (f - O)) = \sum_{i=1}^n a_i \phi_* X_i + b\phi,$$

which is tangent to M . Thus $g = h$ for the frame $\{\phi, Q\}$.

Moreover

$$[\phi, \phi_* X_1, \dots, \phi_* X_n, Q] = [\nu, \nu_* X_1, \dots, \nu_* X_n] = 1,$$

thus proving that Q belongs to the affine normal plane.

The Laplacian of ϕ

We have proved that the immersion

$$\phi(t) = (\nu(t), \nu(t) \cdot (f(t) - O))$$

is umbilical and that the affine metric g coincides with the Blaschke metric h of f . From this we obtain

$$\left(\frac{1}{n} \Delta \nu, \frac{1}{n} \Delta \nu(t) \cdot (f(t) - O) \right) = (-\rho \nu, -\rho \nu \cdot (f - O) + 1),$$

where $O \in \mathbb{R}^{n+1}$ and ρ is the affine mean curvature of f . We conclude that

$$\frac{1}{n} \Delta \phi = -\rho \phi + Q.$$

Proof of the converse-I

To prove the converse, assume that ϕ is umbilic and write $\phi = (\psi, z)$. Define f by the conditions

$$\psi \cdot (f - O) = z; \quad \psi_* X \cdot (f - O) = X(z),$$

for some origin $O \in \mathbb{R}^{n+1}$. These equations imply that $\psi \cdot f_* X = 0$, for any X , and so $\psi = \lambda \nu$, for some $\lambda \in \mathbb{R}$.

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Take a local frame $\{X_1, \dots, X_n\}$ g -orthonormal such that

$$[\phi, \phi_* X_1, \dots, \phi_* X_n, Q] = 1.$$

Then

$$[\psi, \psi_* X_1, \dots, \psi_* X_n] = 1.$$

Proof of the converse-II

So we have

$$[\nu, \nu_* X_1, \dots, \nu_* X_n] = \lambda^{n+1}.$$

Proof of the converse-II

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Arguing as above, one can verify that $g(X, Y) = -\psi_* Y \cdot f_* X$.

Thus

$$g(X, Y) = \lambda h(X, Y).$$

From this we conclude that

$$[\nu, \nu_* X_1, \dots, \nu_* X_n] = \lambda^{n/2}.$$

Comparing with the above formula we obtain $\lambda = 1$, thus proving the theorem.

Thank you!

Obrigado!