

# How to sink a ship

## School on Singularity Theory

### Mini-course on Applications of Singularities

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São Carlos, SP, Brasil

17 – 22 July 2016

# Applications of Singularities — course outline

## 1. Singularities of functions.

Applications:

- ▶ How to sink a ship
- ▶ Catastrophe machines

## 2. Singularities of differential equations with two time scales.

Application:

- ▶ Models for nerve impulse

## 3. Singularities and symmetry.

Application:

- ▶ Deformation of an elastic cube.

**Singularity Theory** studies the dependence on parameters of objects.

Objects come from analysis and geometry, or physics, or from some other science.

The exact values of parameters usually (**generically**) do not have a big influence on the phenomena studied:  
after small changes of parameter values  
quantitative aspects change,  
but qualitative, topological features remain the same.

For some exceptional values of the parameters  
a very small variation of the parameter induces  
a sudden change of qualitative features.

This change is called a bifurcation or catastrophe or perestroika,  
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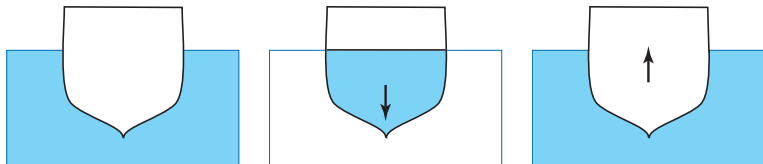
Today we'll use this to sink a ship.

# How a ship floats

**Archimedes** principle ( $\approx$  200 B.C.)

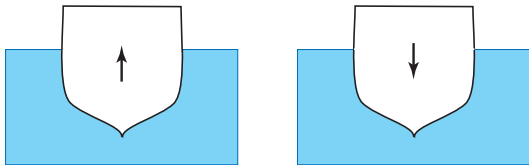
## **Bouyancy**

Force equal and opposite to the weight of the displaced water, applied to the center of mass of the displaced water.



## Forces acting on the ship

**Bouyancy** — Force equal and opposite to the weight of the displaced water, applied to the centre of mass of the displaced water.

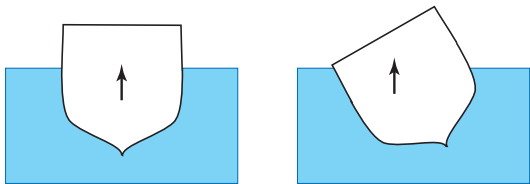


**Weight** — Force applied to centre of mass of the ship.

**Vertical equilibrium** attained at the depth for which weight and buoyancy have the same value.

The position of the centre of mass of the displaced water, when vertical equilibrium is attained is called **centre of buoyancy** of the ship.

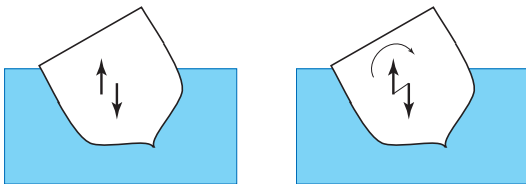
# Ship



The position of the centre of buoyancy depends on the shape of the submerged part of the ship.

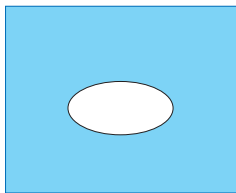
The shape of the submerged part depends on the angle made by the symmetry axis of the ship with the vertical.

When weight and buoyancy are not aligned this creates a **torque**.



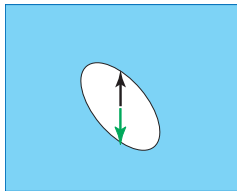
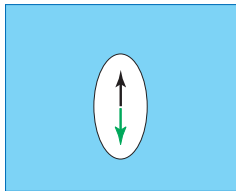
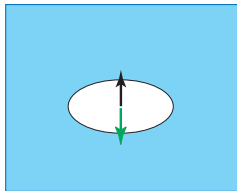


# Submarine



The position of the centre of buoyancy is always the same.

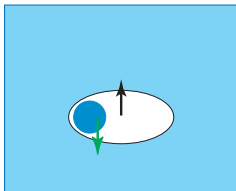
If the density of the submarine is uniform,  
then the centre of mass coincides with the centre of buoyancy.



The submarine is in equilibrium in any position.

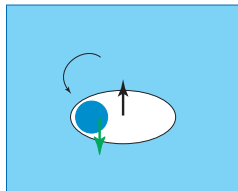
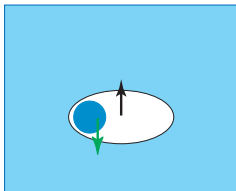
## Submarine with a dense bubble

The position of the centre of buoyancy is always the same.  
If the density of the submarine is not uniform, then  
the centre of mass does not coincide with the centre of buoyancy.



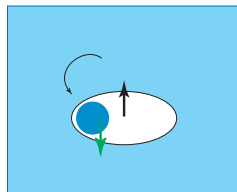
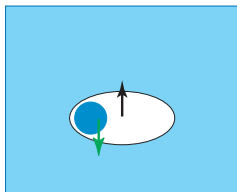
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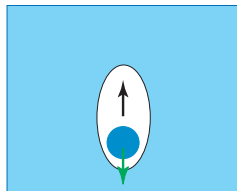


## Submarine with a dense bubble

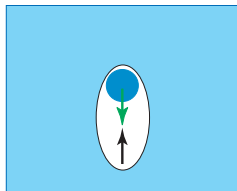
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The submarine has only two equilibrium positions.

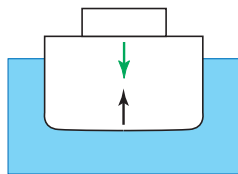


stable equilibrium

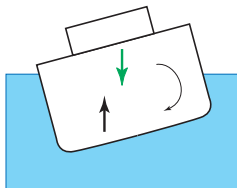


unstable equilibrium

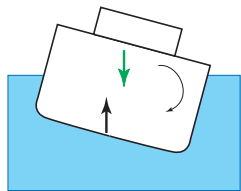
# Ship



equilibrium



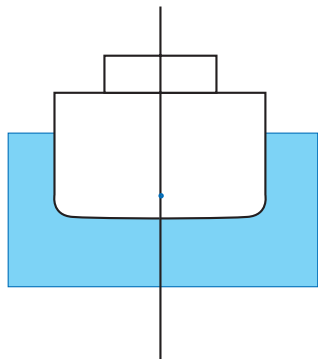
restoring moment



moment.... disastrous

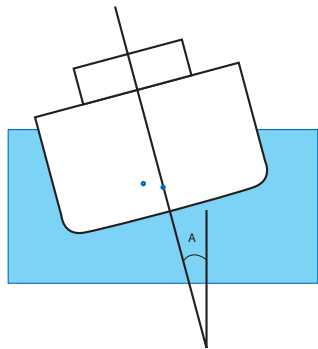
We want to determine the position of the centre of buoyancy (we will paint it on the ship).

## Centre of buoyancy for the ship



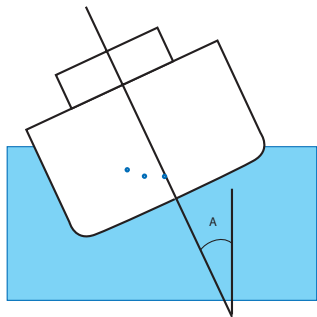
To each angle  $A$  corresponds a position of the centre of buoyancy,

## Centre of buoyancy for the ship



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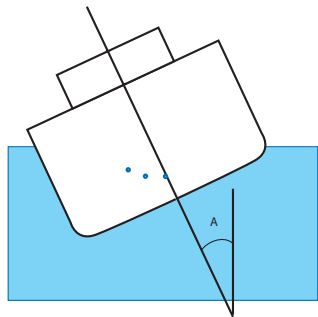
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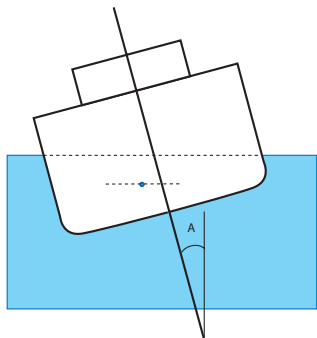
## Centre of buoyancy for the ship



To each angle  $A$  corresponds a position of the centre of buoyancy, defining a curve  $F = f(A)$ .

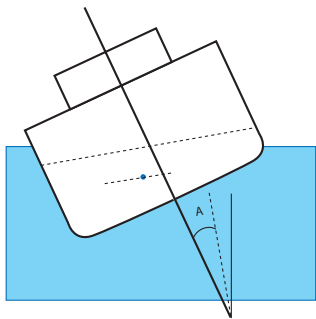
## Centre of buoyancy for the ship

When the angle  $A$  increases



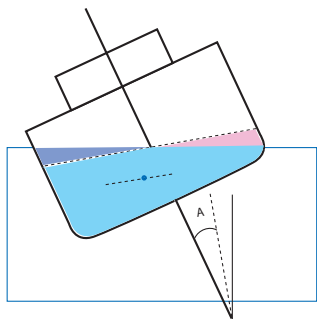
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## Centre of buoyancy for the ship

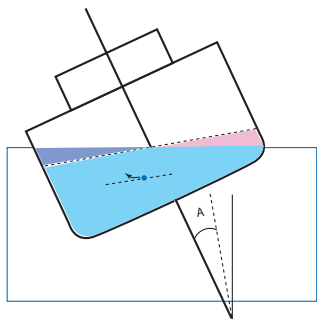
When the angle  $A$  increases



the submerged area on top increases on the slanting side,

## Centre of buoyancy for the ship

When the angle  $A$  increases

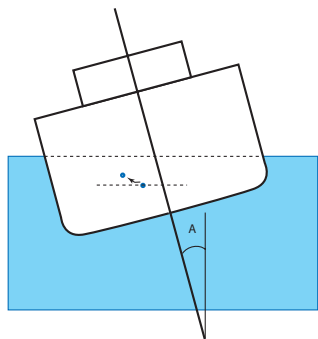


the submerged area on top  
increases on the slanting  
side,

the centre of buoyancy  
moves **up**

## Centre of buoyancy for the ship

When the angle  $A$  increases

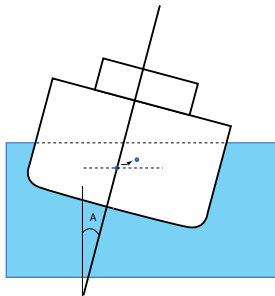
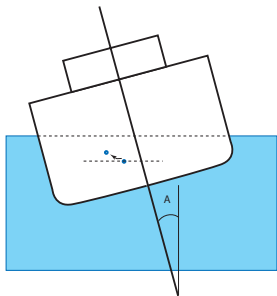


the submerged area on top increases on the slanting side,

the centre of buoyancy moves **up**

## Centre of buoyancy for the ship

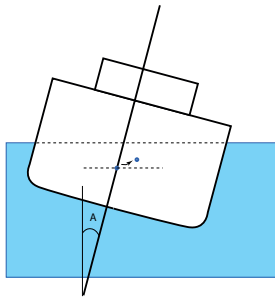
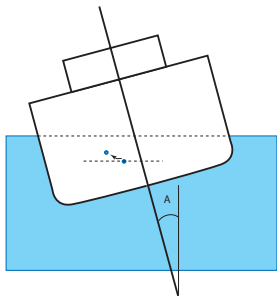
When the angle  $A$  increases the centre of buoyancy moves **up**.



When the angle  $A$  decreases the centre of buoyancy also moves **up**.

## Centre of buoyancy for the ship

When the angle  $A$  increases the centre of buoyancy moves **up**.



When the angle  $A$  decreases the centre of buoyancy also moves **up**.

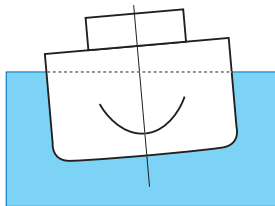
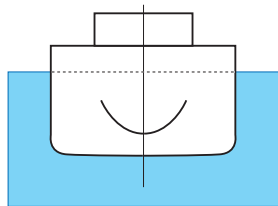
The water line is parallel to the tangent of the graph of  $F$ .

Weight and buoyancy are perpendicular to the graph of  $F$ .



## Centre of buoyancy for the ship

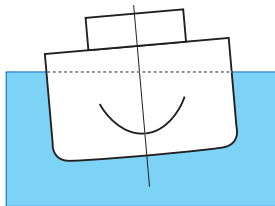
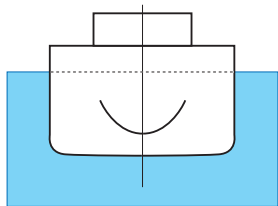
The curve  $F(A)$  of the centres of buoyancy is convex.



Equilibrium occurs at an angle  $A$  if the centre of mass is on a line perpendicular to the curve  $F(A)$

## Centre of buoyancy for the ship

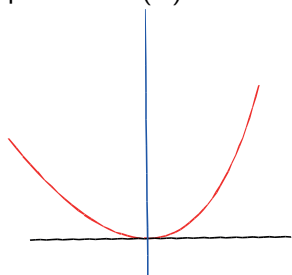
The curve  $F(A)$  of the centres of buoyancy is convex.



Equilibrium occurs at an angle  $A$  if the centre of mass is on a line perpendicular to the curve  $F(A)$  like in the **gravitational catastrophe machine**.

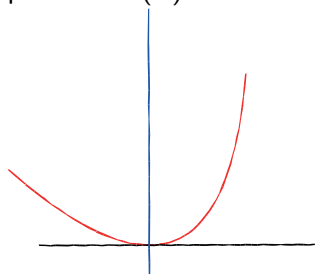
# Gravitational catastrophe machine

The centre of mass should be on a line perpendicular to the parabola  $F(A)$



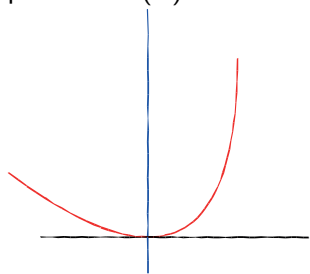
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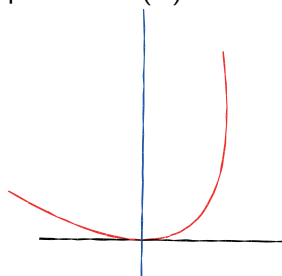
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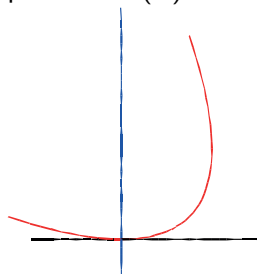
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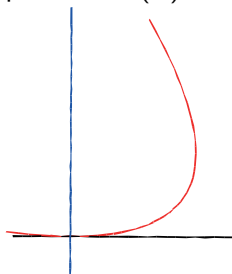
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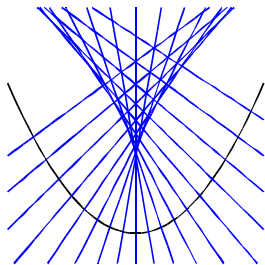
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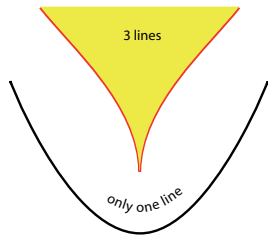
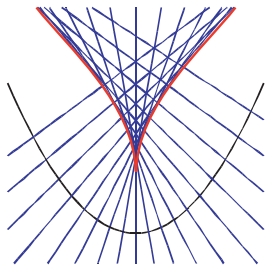




Lines perpendicular to the parabola  $F(A)$

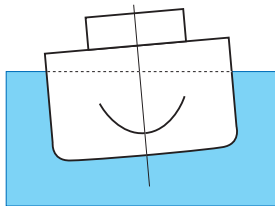
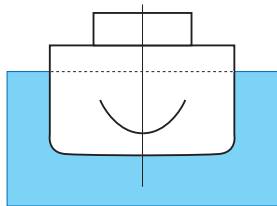


# Lines perpendicular to the parabola $F(A)$

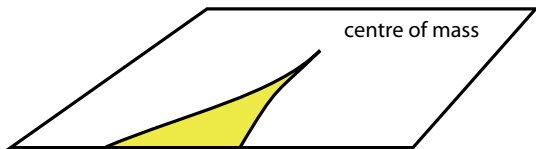
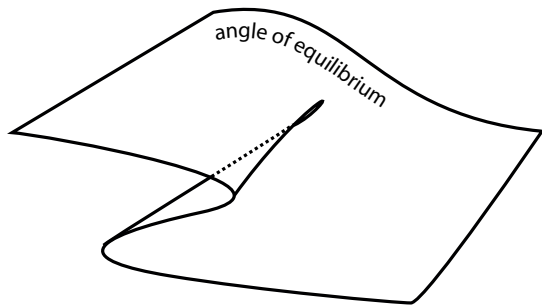


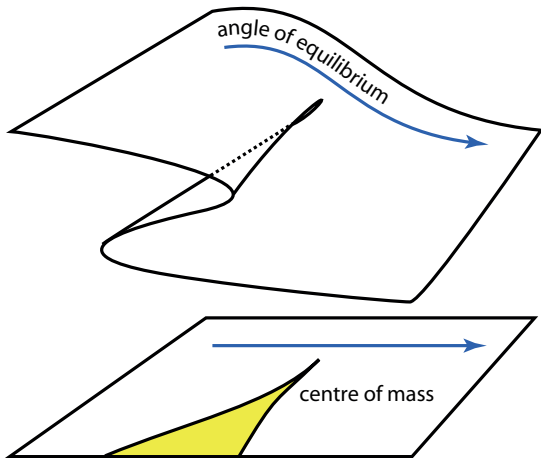
Cusp

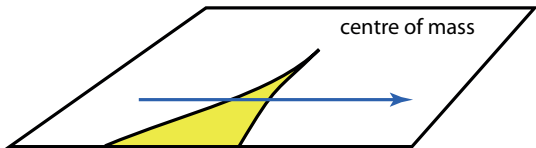
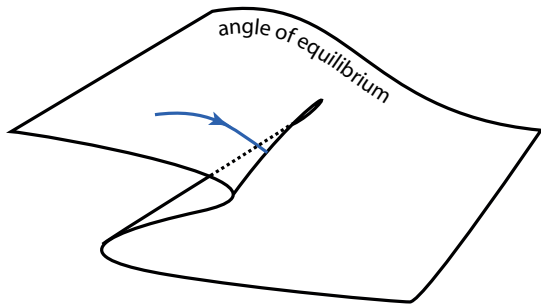
## Straight sided ship

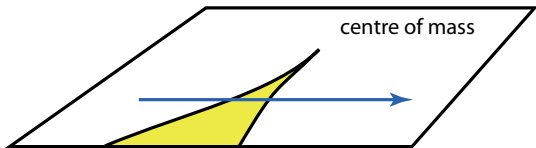
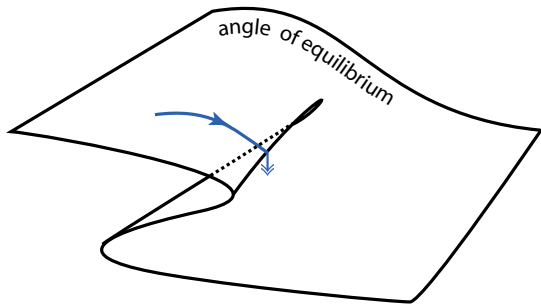


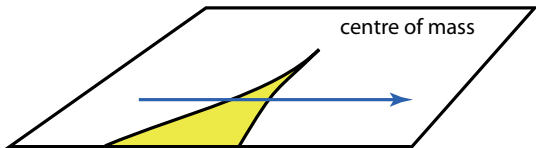
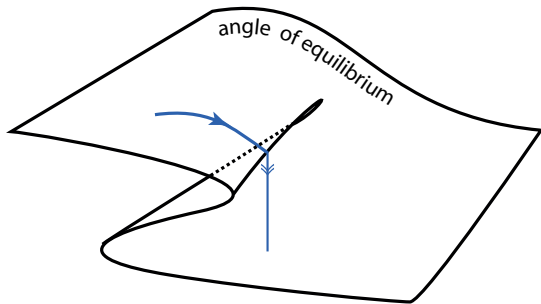
For a “rectangular” ship, the curve  $F(A)$  of the centres of buoyancy is a parabola.



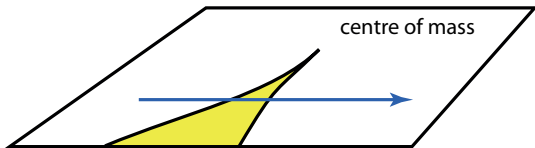
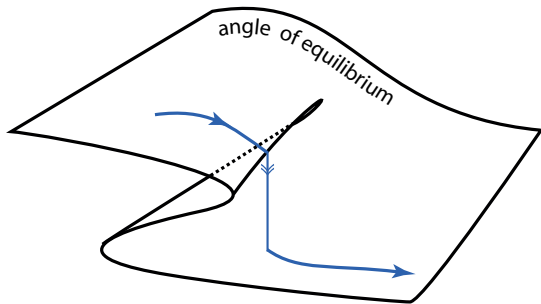












More about jumps — tomorrow!

If you want to know more about ships  
or about catastrophe machines, look at:

T. Poston and I.N. Stewart

*Catastrophe Theory and its Applications*,  
Pitman 1978