

# Singularities with symmetry

## School on Singularity Theory

### Mini-course on Applications of Singularities

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São Carlos, SP, Brasil

17 – 22 July 2016

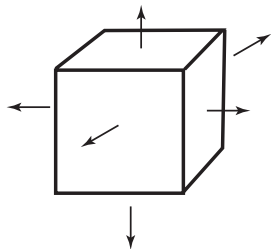
# Deformation of an elastic cube under uniform traction

Dimensions of the deformed cube:  $(l_1, l_2, l_3)$

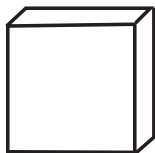
$l_j > 0$

Conservation of volume:  $l_1 l_2 l_3 = 1$

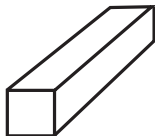
Traction strength:  $\lambda$



Symmetric deformations



$l_1 < l_2 = l_3$   
plate



$l_1 = l_2 < l_3$   
rod

Symmetries of the problem

Permutations of the sides

symmetry group  $S_3$ .

# Model independent treatment

General method, applied to the problem of the cube:

Bifurcation, reduction to kernel

Symmetry, multidimensional kernel

Fixed-point subspaces

Invariant theory

Equivariant singularities

# Bifurcation

Model is an equation  $\dot{x} = g(x, \lambda)$   $x \in \mathbf{R}^n$ .

Equilibrium solutions satisfy  $g(x_0, \lambda_0) = 0$ .

Stability is given by the sign of the eigenvalues of  $D_x g(x_0, \lambda_0)$ .

If all eigenvalues are non-zero, then, locally,

$\exists! x(\lambda)$   $x(\lambda_0) = x_0$  such that  $g(x(\lambda), \lambda) \equiv 0$

and these are all the solutions of  $g(x, \lambda) = 0$ .

(Implicit function theorem)

Without loss of generality, suppose  $g(0, \lambda) = 0$ .

# Bifurcation

Model is an equation  $\dot{x} = g(x, \lambda)$   $x \in \mathbf{R}^n$ ,  $g(0, \lambda) = 0$ .

Bifurcation at  $\lambda = 0$  implies zero is eigenvalue of  $D_x g(0, 0)$

$$\ker D_x g(0, 0) \neq \{0\}$$

Liapunov-Schmidt reduction (Implicit function theorem)  
problem is equivalent to

$$\dot{x} = h(x, \lambda) \quad x \in \ker D_x g(0, 0) \quad h(0, \lambda) = 0$$

Generically,  $\dim \ker D_x g(0, 0) = 1$ .

# Symmetry

Model is an equation  $\dot{x} = g(x, \lambda)$   $x \in \mathbf{R}^n$ .

$\gamma \in \mathbf{O}(n)$  is a symmetry of  $x_0 \in \mathbf{R}^n$

$$\gamma x_0 = x_0$$

$\gamma \in \mathbf{O}(n)$  is a symmetry of  $g$

$$g(\gamma x, \lambda) = \gamma g(x, \lambda)$$

( $g$  is  $\gamma$ -equivariant)

If  $\gamma x_0 = x_0$  and  $D_x g(x_0, \lambda_0) = L$  then  $\gamma L = L\gamma$ .

If  $Lv = 0$  then  $L\gamma v = 0$ .

Generically, in systems with symmetry,  $\dim \ker D_x g(x_0, \lambda_0) > 1$ .

# Symmetry

Example: symmetries of an equilateral triangle

$\mathbf{D}_3$  acting on  $\mathbf{R}^2 \sim \mathbf{C}$  by

$$\rho(z) = e^{2\pi i/3} z \quad \kappa(z) = \bar{z}$$

$\kappa$  is a symmetry of  $x \in \mathbf{R} \subset \mathbf{C}$ .

If  $g(x, \lambda)$  is  $\mathbf{D}_3$ -equivariant with  $D_x g(0, 0) = L$

and if  $Lv = 0$  with  $v \neq 0$  then  $L\rho v = 0$ .

Since  $v \neq 0$  and  $\rho v$  are linearly independent, then  $L \equiv 0$ ,

$\dim \ker D_x g(x_0, \lambda_0) = 2$ .

## Fixed-point subspaces— spontaneous symmetry breaking

$\Gamma \leq \mathbf{O}(n)$  group of symmetries  $\gamma$  of bifurcation problem  $g(x, \lambda)$ .

$\Sigma \leq \Gamma$  subgroup of symmetries of an equilibrium  $x_0 \in \mathbf{R}^n$

isotropy subgroup

All the equilibria with symmetry subgroup  $\Sigma$  lie in the:

### Fixed-point subspace

$$\text{Fix}(\Sigma) = \{x \in \mathbf{R}^n : \gamma x = x \quad \forall \gamma \in \Sigma\}$$

If  $x \in \text{Fix}(\Sigma)$  then  $g(x, \lambda) \in \text{Fix}(\Sigma)$ .

### Action of $\Gamma$ on $V$ is irreducible

if the only subspaces  $W \leq V$

such that  $\gamma w \in W \quad \forall w \in W, \gamma \in \Gamma$

are  $W = \{0\}$  and  $W = V$ .

### Theorem (Equivariant branching lemma)

*If the action of  $\Gamma$  on  $V$  is irreducible, and if  $\Sigma \leq \Gamma$  is an isotropy subgroup with  $\dim \text{Fix}(\Sigma) = 1$ , then, generically, for a  $\Gamma$ -equivariant bifurcation problem  $g(x, \lambda)$ , there is a unique branch with symmetry  $\Sigma$  that bifurcates from the trivial equilibrium at  $\lambda = 0$ .*



## Fixed-point subspaces and the cube

Symmetry group  $\Gamma = \mathbf{S}_3$

acting on the surface  $\{(\ell_1, \ell_2, \ell_3) : \ell_j > 0 \quad \ell_1 \ell_2 \ell_3 = 1\} \subset \mathbf{R}^3$

$\mathbf{S}_3$  is generated by:

$$P_3(\ell_1, \ell_2, \ell_3) = (\ell_2, \ell_3, \ell_1) \quad P_2(\ell_1, \ell_2, \ell_3) = (\ell_2, \ell_1, \ell_3)$$

action of  $\mathbf{S}_3$  on the surface is isomorphic to  $\mathbf{D}_3$  acting on  $\mathbf{R}^2 \sim \mathbf{C}$

$$\rho(z) = e^{2\pi i/3} z \approx P_3 \quad \kappa(z) = \bar{z} \approx P_2$$

cube  $\ell_1 = \ell_2 = \ell_3$  identified to origin (maximum symmetry)

$\dim \text{Fix}(\Sigma) = 1$  for  $\Sigma = \mathbf{Z}_2 = \{\kappa, Id\}$ .

A branch with symmetry  $\kappa$  : rods or plates.

Three symmetric copies of the branch.

are they rods or are they plates?

## Invariant functions

$f : \mathbf{R}^n \longrightarrow \mathbf{R}$  is  $\Gamma$ -invariant if

$$f(\gamma x) = f(x) \quad \forall x \in \mathbf{R}^n \quad \forall \gamma \in \Gamma$$

Example:  $\mathbf{D}_3$ -invariant functions

$$u(x, y) = x^2 + y^2 \qquad v(x, y) = x^3 - 3xy^2$$

in complex notation

$$u(z) = z\bar{z} \qquad v(z) = \operatorname{Re}(z^3)$$

Every  $\mathbf{D}_3$ -invariant  $C^\infty$  function can be written in the form

$$f(x, y) = p(u(x, y), v(x, y))$$

where  $p$  is a  $C^\infty$  function of 2 variables.

(by the Hilbert-Weyl-Schwarz theorem)

# Equivariant vector fields

$F : \mathbf{R}^n \longrightarrow \mathbf{R}^n$  is  $\Gamma$ -equivariant if

$$F(\gamma x) = \gamma F(x) \quad \forall x \in \mathbf{R}^n \quad \forall \gamma \in \Gamma$$

If  $f : \mathbf{R}^n \longrightarrow \mathbf{R}$  is  $\Gamma$ -invariant

and if  $F : \mathbf{R}^n \longrightarrow \mathbf{R}^n$  is  $\Gamma$ -equivariant

then  $f(x)F(x)$  is also  $\Gamma$ -equivariant.

## Equivariant vector fields

Example:  $\mathbf{D}_3$ -equivariant vector fields

$$X(x, y) = (x, y) \qquad Y(x, y) = (x^2 - y^2, -2xy)$$

in complex notation

$$X(z) = z \qquad Y(z) = (\bar{z})^2$$

Every  $\mathbf{D}_3$ -equivariant vector field of class  $C^\infty$  can be written in the form

$$F(x, y) = p(u(x, y), v(x, y))X(x, y) + q(u(x, y), v(x, y))Y(x, y)$$

where  $p$  and  $q$  are  $C^\infty$  functions of 2 variables.

(by Poénaru's theorem)

## $D_3$ -equivariant vector fields generated by:

Invariant functions

$$u(x, y) = x^2 + y^2$$

$$v(x, y) = x^3 - 3xy^2$$

Equivariant vector fields

$$X(x, y) = (x, y)$$

$$Y(x, y) = (x^2 - y^2, -2xy)$$

$D_3$ -equivariant Taylor expansions:

degree	term
1	$X$
2	$Y$
3	$uX$
4	$uY \quad vX$
5	$u^2X \quad vY$

# Consequence

## Theorem

*The rod and plate solutions that bifurcate from the cube are unstable.*

## Proof

Model is an equation  $(\dot{x}, \dot{y}) = g(x, y, \lambda)$   
 $(x, y) \in \mathbf{R}^2$  with  $g$   $\mathbf{D}_3$ -equivariant.

$$g(x, y, \lambda) = p(u, v, \lambda) \begin{pmatrix} x \\ y \end{pmatrix} + q(u, v, \lambda) \begin{pmatrix} x^2 - y^2 \\ -2xy \end{pmatrix}$$

Bifurcating solutions are in  $\text{Fix}(\mathbf{Z}_2) = \{(x, 0)\}$ , hence they satisfy

$$xp + x^2q = 0$$

and if  $x \neq 0$  then

$$p + xq = 0$$

## Proof of instability

Write  $p_x = \frac{\partial p}{\partial x} = 2x \frac{\partial p}{\partial u} + 3(x^2 - y^2) \frac{\partial p}{\partial v}$  and similarly for  $q_x, p_y, q_y$ .

Then  $D_{(x,y)}g(x, y, \lambda)$  is:

$$\begin{pmatrix} xp_x + p + (x^2 - y^2)q_x + 2xq & xp_y + (x^2 - y^2)q_y - 2yq \\ yp_x - 2xyq_x - 2yq & ypy + p - 2xyq_y - 2xq \end{pmatrix}$$

In  $\text{Fix}(\mathbf{Z}_2) = \{(x, 0, \lambda)\}$ ,  $D_{(x,y)}g(x, 0, \lambda)$  is:

$$\begin{pmatrix} p + 2xq + xp_x + x^2q_x & xp_y + x^2q_y \\ 0 & p - 2xq \end{pmatrix}$$

Eigenvalues:

$$p + 2xq + xp_x + x^2q_x = p + 2xq + O(x^3) \qquad p - 2xq$$

## Proof of instability

Eigenvalues of  $D_{(x,y)}g(x, 0, \lambda)$ :

$$p + 2xq + O(x^3)$$

$$p - 2xq$$

In  $\text{Fix}(\mathbf{Z}_2) = \{(x, 0)\}$  solutions of  $g = 0$  satisfy

$$p + xq = 0$$

Hence the eigenvalues are

$$p + 2xq + O(x^3) = xq + O(x^3)$$

$$p - 2xq = -3xq$$

that have opposite signs for small  $x \neq 0$  — the branch is unstable.



## Equivariant singularities

How to use singularity theory to find stable branches of  $g(x, y, \lambda) = pX + qY$ :

- ▶ Find a more degenerate problem nearby (organising centre)  
Suppose  $p(0, 0, 0) = 0$  and **also**  $q(0, 0, 0) = 0$ .
- ▶ Perturb the degenerate problem generically (within the class of  $\mathbf{D}_3$ -equivariant bifurcations) and see what happens.

If  $p(0, 0, 0) = 0 = q(0, 0, 0)$ , then, up to changes of coordinates that preserve the  $\mathbf{D}_3$  symmetry,  $g$  is like:

$$h(z, \lambda) = (u - \lambda)z + (u + mv)\bar{z}^2$$

# Bifurcation diagrams

Organising centre



solid line — stable

$$h(z, \lambda) = (u - \lambda)z + (u + mv)\bar{z}^2$$

dashed line — unstable

# Bifurcation diagrams

Generic perturbation

$$h(z, \lambda) = (u - \lambda)z + (u + mv + \alpha)\bar{z}^2$$

$\alpha > 0$

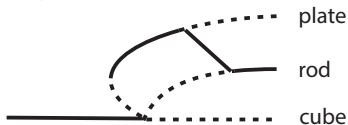


solid line — stable

dashed line — unstable

$\alpha < 0$

$m > 0$



$\alpha < 0$

$m < 0$



## References

- ▶ M. Golubitsky, I.N. Stewart, W. Schaeffer, *Singularities and Groups in Bifurcation Theory, vol II* Springer-Verlag (1984)
- ▶ M. Golubitsky, I.N. Stewart, *The Symmetry Perspective: From Equilibrium to Chaos in Phase Space and Physical Space*, Birkäuser